

SEAN O'CONNOR

sean@soconnor.dev • sso005@bucknell.edu • soconnor.dev •

RESEARCH INTERESTS

My research focuses on advancing human-robot interaction through improved experimental methodologies and accessible research tools. I am particularly interested in Wizard-of-Oz experimental frameworks, reproducibility in HRI studies, and developing platforms that democratize access to HRI research across disciplines. My work with HRISudio addresses critical challenges in experimental reproducibility and cross-platform robot control, enabling researchers without specialized programming expertise to conduct rigorous HRI studies. I am passionate about exploring how we can make robot behaviors more trustworthy and explainable, particularly through transparent experimental design and comprehensive data logging. Looking forward, I aim to investigate how standardized experimental frameworks can advance our understanding of human-robot trust, collaboration dynamics, and the design of intuitive robot interfaces across diverse application domains.

EDUCATION

BOSTON UNIVERSITY

Master of Science in Computer Engineering

BOSTON, MA

Expected May 2027

BUCKNELL UNIVERSITY

Bachelor of Science in Computer Science and Engineering, Honors

LEWISBURG, PA

May 2026

Engineering GPA: 3.92/4.0 • Overall GPA: 3.71/4.0 • Magna Cum Laude • Dean's List: Seven Semesters

James M. Pommersheim Research & Innovation in Engineering Award — awarded to the engineering student who has achieved through creative effort outstanding work of scholarship or invention

PUBLICATIONS

- [1] Sean O'Connor. A web-based wizard-of-oz platform for collaborative and reproducible human-robot interaction research. Bachelor's honors thesis, Bucknell University, Lewisburg, PA, 2026.
- [2] Sean O'Connor and L. Felipe Perrone. HRISudio: A Framework for Wizard-of-Oz Experiments in Human-Robot Interaction Studies (Late Breaking Report). In *2024 33rd IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*, 2024.
- [3] Sean O'Connor and L. Felipe Perrone. A Web-Based Wizard-of-Oz Platform for Collaborative and Reproducible Human-Robot Interaction Research. In *2025 34th IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*, Eindhoven, The Netherlands, 2025.

RESEARCH EXPERIENCE

HUMAN-ROBOT INTERACTION RESEARCH

Lead Researcher - HRISudio Platform Development

BUCKNELL UNIVERSITY

Jan 2023 – Present

Advisor: Dr. L. Felipe Perrone, Computer Science Department

Research Commitment: 3.5 credits of individual study (CSCI 278/378) across 6 semesters

- Developing HRISudio, a novel web-based platform addressing reproducibility challenges in Wizard-of-Oz HRI studies, with two first-author publications at IEEE RO-MAN 2024 and 2025
- Architected modular plugin system enabling cross-platform robot control (NAO, Pepper, custom platforms) through JSON-defined interfaces, eliminating need for specialized programming knowledge
- Implemented WebSocket-based bidirectional communication protocols for low-latency robot teleoperation with real-time state synchronization
- Designed comprehensive data logging system capturing interaction timelines, robot states, and experimental conditions with microsecond precision for reproducibility analysis
- Developed RESTful API leveraging Robot Operating System (ROS) for extensible robot integration across multiple platforms
- Currently developing honors thesis evaluating platform effectiveness through user studies and analyzing impact on interdisciplinary HRI research accessibility
- Conducted systematic literature review identifying key challenges in WoZ methodology reproducibility, informing platform design decisions and feature prioritization

INTERDISCIPLINARY RESEARCH COLLABORATION

Computer Science Research Assistant - Chemical Engineering Department

BUCKNELL UNIVERSITY

Aug 2023 – May 2025

Collaborating with Chemical Engineering Department on Environmental Monitoring

- Developed automated data collection and analysis tools for environmental research, processing real-time sensor data streams for atmospheric and water quality monitoring

- Built custom Python pipelines integrating multiple data sources, enabling researchers to identify patterns in environmental data that informed conference presentations
- Bridged computer science expertise with domain-specific research needs, demonstrating ability to collaborate across disciplines

ROBOLAB@BUCKNELL

BUCKNELL UNIVERSITY

Founding Member and Research Participant

Sep 2023 - Present

Interdisciplinary lab bridging Computer Science and Psychology perspectives on HRI

- Participate in weekly research seminars exploring human-robot trust, automation bias, and ethical implications of autonomous systems
- Contribute to discussions on experimental design for HRI studies, bringing technical perspective to psychological research questions

TEACHING EXPERIENCE

COMPUTER SCIENCE DEPARTMENT

BUCKNELL UNIVERSITY

Teaching Assistant - Software Engineering & Design

Jan 2024 - Present

- Mentor 150+ students in software engineering principles, design patterns, and collaborative development practices
- Developed automated testing frameworks with personalized feedback, improving learning outcomes while streamlining assessment processes
- Created supplementary materials connecting theoretical concepts to real-world applications, drawing from industry experience
- Hold regular office hours and code review sessions, fostering deep understanding of software architecture principles

Computer Science Tutor - Engineering Study Spot

Aug 2024 - Dec 2024

- Provided one-on-one tutoring across the entire computer science curriculum, from introductory programming to advanced algorithms
- Developed personalized learning strategies for students with diverse backgrounds and learning styles

ENGINEERING DEPARTMENT

BUCKNELL UNIVERSITY

Teaching Assistant - Engineering Design Experience

Aug 2023 - Dec 2023

- Guided 40+ engineering students through Arduino programming and breadboard circuit design
- Supervised hands-on laboratory sessions involving microcontroller programming and sensor integration
- Facilitated discussions on engineering ethics and the societal implications of embedded system design

PHYSICS DEPARTMENT

BUCKNELL UNIVERSITY

Teaching Assistant - Experimental Physics Laboratory

Aug 2023 - May 2024

- Instructed 100+ students in experimental design, data analysis, and scientific writing
- Emphasized connection between theoretical physics principles and experimental validation
- Guided students through error analysis and uncertainty quantification in experimental measurements

SELECTED PROJECTS

Computer System from Scratch - Nand2Tetris (ECEG 431)

HDL/Assembly/Java

- Built complete computer system from NAND gates through operating system, demonstrating comprehensive understanding of computer architecture
- Designed and simulated all hardware components including logic gates, ALU, RAM, and CPU using hardware description language
- Developed complete software stack: assembler for machine code translation, virtual machine translator for intermediate code, and compiler for high-level object-oriented language
- Implemented functional operating system with memory management, I/O handling, and graphics capabilities
- Technologies: Hardware Description Language (HDL), Assembly, Jack (object-oriented language), Java

HRIStudio - Web-Based Wizard-of-Oz Platform

TypeScript/React/WebRTC

- Architected full-stack web application for managing HRI experiments with real-time robot control interfaces
- Implemented WebSocket-based bidirectional communication protocols for low-latency robot teleoperation
- Designed RESTful API leveraging Robot Operating System with JSON-defined plugins for extensibility across multiple robot platforms
- Created comprehensive logging system capturing interaction data, timestamps, and experimental conditions for reproducibility
- Technologies: Next.js, React, TypeScript, Node.js, WebSockets, PostgreSQL, Docker

Autonomous Vehicle Control System - Chem-E-Car Competition

C++/Arduino

- Designed embedded control system for autonomous hydrogen fuel cell-powered vehicle using finite state machine architecture
- Implemented real-time sensor fusion combining spectrometer readings and power monitoring with calculated stopping algorithms

- Developed PlatformIO-based build system with hardware abstraction layer for testing and simulation
- Achieved precise distance control ($\pm 10\text{cm}$) through chemical reaction timing at AIChE National Competition
- Technologies: C++, Arduino, PlatformIO, I2C/SPI protocols, finite state machines

Formula One Performance Prediction Using Machine Learning

Python/ML

- Developed ensemble machine learning models (LightGBM, XGBoost, Random Forest) to predict F1 lap times with high accuracy
- Engineered features from weather data, track characteristics, and historical performance using domain knowledge
- Implemented cross-validation and hyperparameter optimization for model evaluation across multiple racing circuits
- Analyzed feature importance to understand factors influencing racing performance
- Technologies: Python, LightGBM, XGBoost, Random Forest, pandas, scikit-learn, FastF1 API

Real-time Racing Statistics Platform

TypeScript/Next.js

- Built production system serving 1500+ concurrent users and 250k+ monthly visitors
- Implemented WebSocket-based real-time data streaming with automatic reconnection and state synchronization
- Designed responsive UI with accessibility features meeting WCAG 2.1 AA standards
- Optimized database queries reducing page load times by 60% through intelligent caching and indexing
- Technologies: Next.js, TypeScript, PostgreSQL, Docker, DigitalOcean

PROFESSIONAL EXPERIENCE

RIVERHEAD RACEWAY

RIVERHEAD, NY

Software Developer

Oct 2020 – Present

- Architected and deployed production systems handling 250k+ monthly users and \$100,000+ in payment processing
- Led digital transformation initiative, replacing legacy paper-based systems with modern web applications
- Implemented CI/CD pipelines, containerization, and infrastructure as code using Docker and GitHub Actions
- Developed RESTful APIs and microservices architecture for scalable, maintainable systems

IT Administrator

Oct 2020 - Apr 2024

- Modernized IT infrastructure from consumer to enterprise-grade systems, improving uptime to 99.9%
- Implemented comprehensive backup and disaster recovery protocols protecting critical business data
- Automated system administration tasks using PowerShell and Bash scripting

MILLER PLACE SCHOOL DISTRICT

MILLER PLACE, NY

Information Technology Intern

Sep 2020 - May 2022

- Supported 1000+ students and faculty during COVID-19 transition to remote learning
- Deployed and maintained educational technology platforms and troubleshooted hardware/software issues

LEADERSHIP & ACTIVITIES

AICHE CHEM-E-CAR COMPETITION TEAM

BUCKNELL UNIVERSITY

President, Electrical/Mechanical Team Lead

Jan 2023 – Present

- Led 15-member interdisciplinary team in designing autonomous chemical-powered vehicles for national competition
- Introduced agile development methodologies and version control practices to hardware development process
- Mentored junior members in embedded systems programming and control theory

BUCKNELL COFFEE SOCIETY

BUCKNELL UNIVERSITY

Co-Founder and Treasurer

Oct 2023 – Present

- Co-established campus organization promoting coffee education and community building
- Manage \$5,000+ annual budget, coordinate events, and maintain vendor relationships
- Organized educational workshops on coffee science, brewing techniques, and sustainability

CONFERENCES & PRESENTATIONS

IEEE RO-MAN 2025

EINDHOVEN, THE NETHERLANDS

34th International Conference on Robot and Human Interactive Communication

Aug 2025

- Presented: "A Web-Based Wizard-of-Oz Platform for Collaborative and Reproducible Human-Robot Interaction Research"

IEEE RO-MAN 2024

PASADENA, CA

33rd International Conference on Robot and Human Interactive Communication

Aug 2024

- Presented: "HRISudio: A Framework for Wizard-of-Oz Experiments in HRI Studies" (Late Breaking Report)

AICHE ANNUAL STUDENT CONFERENCE

SAN DIEGO, CA

Chem-E-Car Performance Competition

Oct 2024

- Competed in National Chem-E-Car Performance Competition with autonomous hydrogen fuel cell vehicle
- Presented poster on safety-critical embedded systems design

- Placed 2nd overall in regional Chem-E-Car Competition

RELEVANT COURSEWORK

Robotics & Human-Robot Interaction: Human-Robot Interaction, Individual Study in HRI (3.5 credits)

Artificial Intelligence & Machine Learning: Artificial Intelligence with Neural Nets (in progress), Data Mining, Image Processing & Analysis (in progress)

Systems & Embedded: Operating Systems Design, Computer Systems, Embedded Computer Systems, Real-time Control Systems

Software Engineering: Software Engineering & Design, Algorithm Design & Analysis, Programming Language Design

Research Methods: Research Methods in Computer Science, Probability & Statistics, Experimental Design

TECHNICAL SKILLS

Robotics & HRI: ROS/ROS2, Gazebo, NAO/Pepper SDK, WebSockets, Wizard-of-Oz Methodology, Robot Teleoperation, Computer Vision

Embedded Systems & Hardware: Arduino, Raspberry Pi, I2C/SPI Protocols, Sensor Integration, Real-time Control, Finite State Machines

Machine Learning & AI: PyTorch, TensorFlow, scikit-learn, LightGBM, XGBoost, OpenCV, pandas, numpy, Jupyter

MLOps & AI Deployment: Weights & Biases (W&B), HuggingFace Transformers, Experiment Tracking, Model Versioning, Transfer Learning

Programming Languages: Python, C/C++, JavaScript/TypeScript, Java, MATLAB, SQL, Bash, LaTeX

Research & Development: Git/GitHub, Docker, Experimental Design, Statistical Analysis (R), Data Visualization, Technical Writing

Web & Systems: React, Node.js, Next.js, REST APIs, PostgreSQL, Linux, Cloud Computing, Distributed Systems

HONORS & AWARDS

- James M. Pommersheim Research and Innovation in Engineering Award — Bucknell University College of Engineering (2026)
- Dean's List (7 semesters): Fall 2022, Fall 2023, Spring 2024, Fall 2024, Spring 2025, Fall 2025, Spring 2026
- GPA: 3.71/4.0 • Engineering GPA: 3.92/4.0 • Magna Cum Laude
- AIChE Mid-Atlantic Chem-E-Car Competition - 2nd Place (2024)